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Lecture Notes for November, 2000

Schöning's random-restart hill-climbing *k*-SAT algorithm

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The Algorithm

Schöning [2] considered the following very simple algorithm for k-SAT (i.e. boolean formula satisfiability, in which the formula is a disjunction of k-variable clauses):

Repeat *K* times:

- 1. Choose a random assignment of truth values for all variables
- 2. Repeat 3*n* times:
 - (a) Find an unsatisfied clause for the current truth assignment
 - (b) Choose randomly one of the *k* variables from the clause and change its assignment from true to false or vice versa

If this sequence of random experiments ever finds a satisfying assignment, we know that the formula is satisfiable and can halt. Each trial can be performed in time $\mathcal{O}(mn)$, where m is the number of clauses and n the number of variables, so the overall running time is K times a polynomial. The question is, how big does K need to be to have high probability of finding a satisfying assignment?

To analyze this algorithm, assume that the formula is satisfiable, and let A^* be some particular satisfying assignment (choose one arbitrarily if there is more than one). Then, for any other truth assignment A, define d(A) to be the Hamming distance from A to A^* ; that is, the number of variables that would have to be flipped to get to the satisfying assignment A^* .

What happens to d(A) in the inner loop of the algorithm? At each step, we pick an unsatisfied clause of the formula. Since this clause is satisfied by A^* , we know that A and A^* differ on at least one of the k variables of this clause. By flipping a randomly chosen variable, we know that with probability at least 1/k we choose one of the variables where they differ, and reduce d by one. With probability at most (k-1)/k, though, we can increase d by one.

Drunkard's Walk

So, the behavior of d in the inner loop can be described by a random walk, in which we start at some positive integer i and step to i-1 with probability 1/k or to i+1 with probability (k-1)/k. If we ever get to zero, we succeed. What is the probability that, starting from i, we ever get to zero?

Let's let p(i) denote this probability. We have a nice recurrence: if we're at position i, then we have probability 1/k of moving to i-1 (with probability p(i-1) of continuing from there to zero) and probability (k-1)/k of moving to i+1 (with probability p(i+1) of continuing from there to zero). So,

$$p(i) = \frac{1}{k}p(i-1) + \frac{k-1}{k}p(i+1).$$

Turning this around, we see that

$$p(i+1) = \frac{k}{k-1}p(i) - \frac{1}{k-1}p(i-1),$$

a recurrence similar to that for the Fibonacci numbers. We could solve this easily if only we knew the base cases. Obviously, p(0) = 1, but we still need to calculate p(1).

Consider what can happen if the random walk reaches position one. With probability 1/k, it moves immediately to position zero and halts. But with probability (k-1)/k, it moves to position two. From there, it might continue to remain forever at positions greater than one, or it might (with probability p(1)) eventually return to position one. If we ever do return to position one, we again have probability p(1) of ever reaching zero. Thus

$$p(1) = \frac{1}{k} + \frac{k-1}{k}(p(1))^{2}.$$

This is a quadratic equation, with two roots. We can either use the quadratic formula or direct substitution to see that the roots are actually 1/(k-1) and 1. The root we want turns out to be 1/(k-1).

Lemma 1

$$p(i) = \frac{1}{(k-1)^i}.$$

Proof: We have seen that this holds for the base cases p(0) = 1 and p(1) = 1/(k-1). The result follows by induction, since plugging in this value for p(i) and p(i-1) in the recurrence gives

$$p(i+1) = \frac{k}{k-1}p(i) - \frac{1}{k-1}p(i-1)$$

$$= \frac{k}{k-1} \cdot \frac{1}{(k-1)^i} - \frac{1}{k-1} \cdot \frac{1}{(k-1)^{i-1}}$$

$$= \frac{k}{(k-1)^{i+1}} - \frac{k-1}{(k-1)^{i+1}}$$

$$= \frac{1}{(k-1)^{i+1}}.$$

Algorithm Analysis

There are two ways in which the random walk above is not an accurate model of the behavior of d(A) in Schöning's algorithm. First, if we ever find a clause containing two or more variables for which A differs from A^* , then the probability of stepping to d(A) - 1 grows and the probability of stepping to d(A) + 1 shrinks, but this can only increase the overall probability of finding a satisfying assignment.

More importantly, we terminate the random walk after 3n steps, instead of allowing it to continue ad infinitum. Schöning goes through a more careful analysis than the one above, showing that this early termination reduces the probability of reaching zero by a negligable amount.

So, what is the probability that a single iteration of the outer loop reaches a satisfying assignment? After we have selected our initial assignment A, the probability is (modulo the inaccuracies noted above) p(d(A)), so the overall probability is just the average of this quantity over all possible sets. Any symmetric difference $A \oplus A^*$ is equally likely, so we get the formula

$$\sum_{i=0}^{n} \frac{1}{2^{n}} \binom{n}{i} \frac{1}{(k-1)^{i}} = (2 - \frac{2}{k})^{-n}.$$

For instance, for 3-SAT, we get probability $(3/4)^n$ of finding a satisfying assignment in a single iteration, so the number of iterations we need overall is roughly $(4/3)^n$.

More generally we can apply this technique to any (k, d)-CSP problem, by finding unsatisfied constraints and finding a random new value for a random variable in the constraint. We get probability 1/(d-1)k of reducing the Hamming distance by this random choice, and the same analysis above shows that we need roughly $(d(1-1/k))^n$ iterations to find a satisfying assignment.

Theorem 1 Schöning's algorithm finds a solution to any satisfiable (k, d)-CSP problem, with high probability, in time $(d(1-1/k))^n n^{\mathcal{O}(1)}$.

Although better algorithms are known for k = 2, this approach provides the best known algorithms for k-SAT (d = 2), as well as for other CSP problems where both k and d are greater than two.

It would be of interest to find problems other than CSP for which this random-walk approach is useful. Another direction of research is derandomization – the best known deterministic algorithm for *k*-SAT can be viewed as a derandomized version of Schöning's algorithm [1] but its time bounds are not as good.

References

- [1] E. Dantsin, A. Goerdt, E. A. Hirsch, and U. Schöning. Deterministic algorithms for *k*-SAT based on covering codes and local search. *Proc. 27th Int. Coll. Automata, Languages and Programming*, 2000. http://logic.pdmi.ras.ru/~hirsch/abstracts/icalp00.html.
- [2] U. Schöning. A probablistic algorithm for *k*-SAT and constraint satisfaction problems. *Proc. 40th Symp. Foundations of Computer Science*, IEEE, October 1999, pp. 410–414.